

Stochastic Interface Equations

*A physicist's short story on
"Randomness", Conservation laws and
Modeling*

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Acknowledgments

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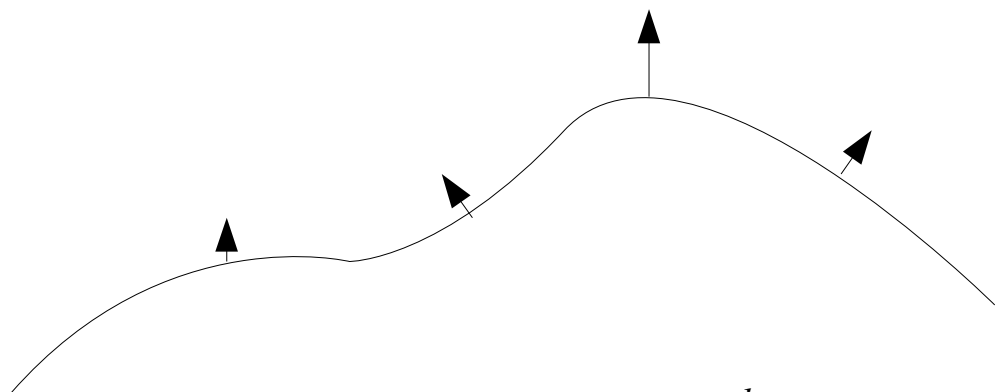
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Outline

- 1) Interface dynamics, experiments and modeling
- 2) Local Interface Equations (LIEs)
- 3) Characterizing a stochastic interface, Scaling
- 4) Case study of Hele-Shaw cells
- 5) Summary

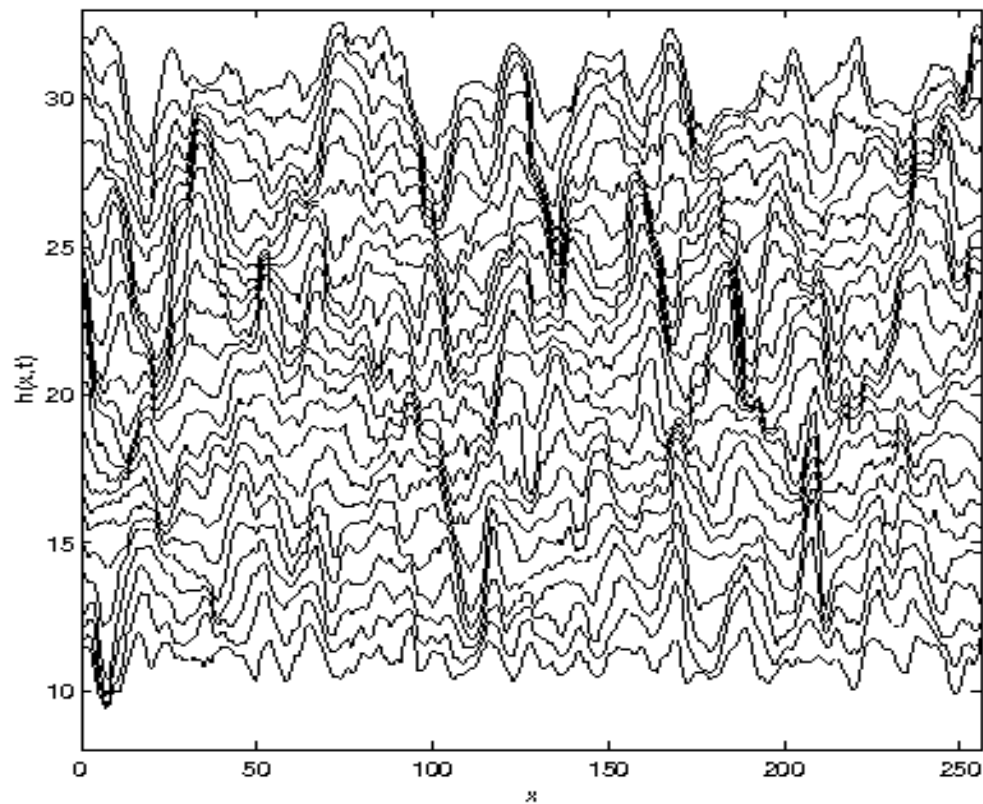
Interface Dynamics



$$h(x, t) ; x \in \mathbb{R}^d$$

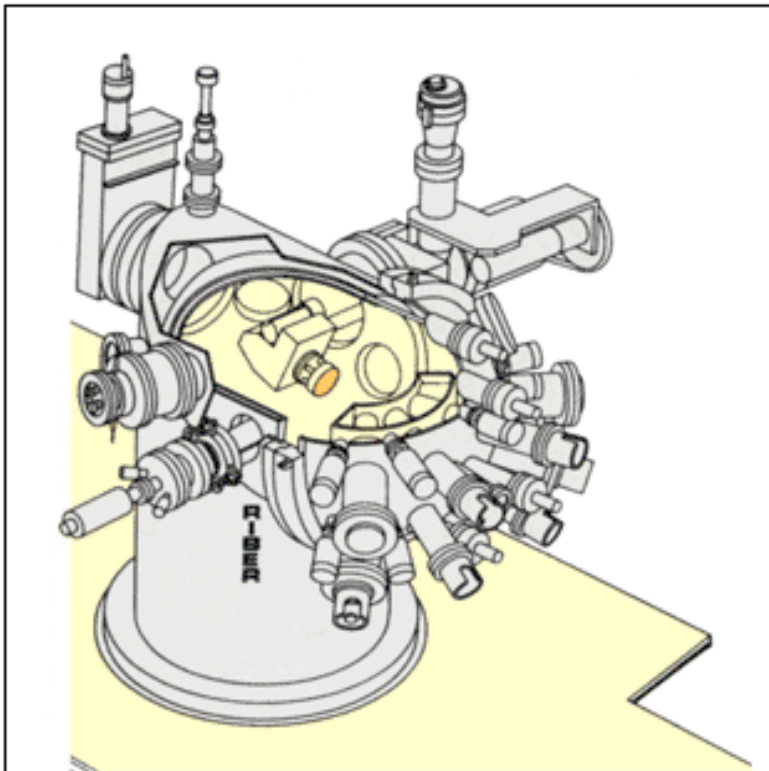
Dimensionality d

Time series:

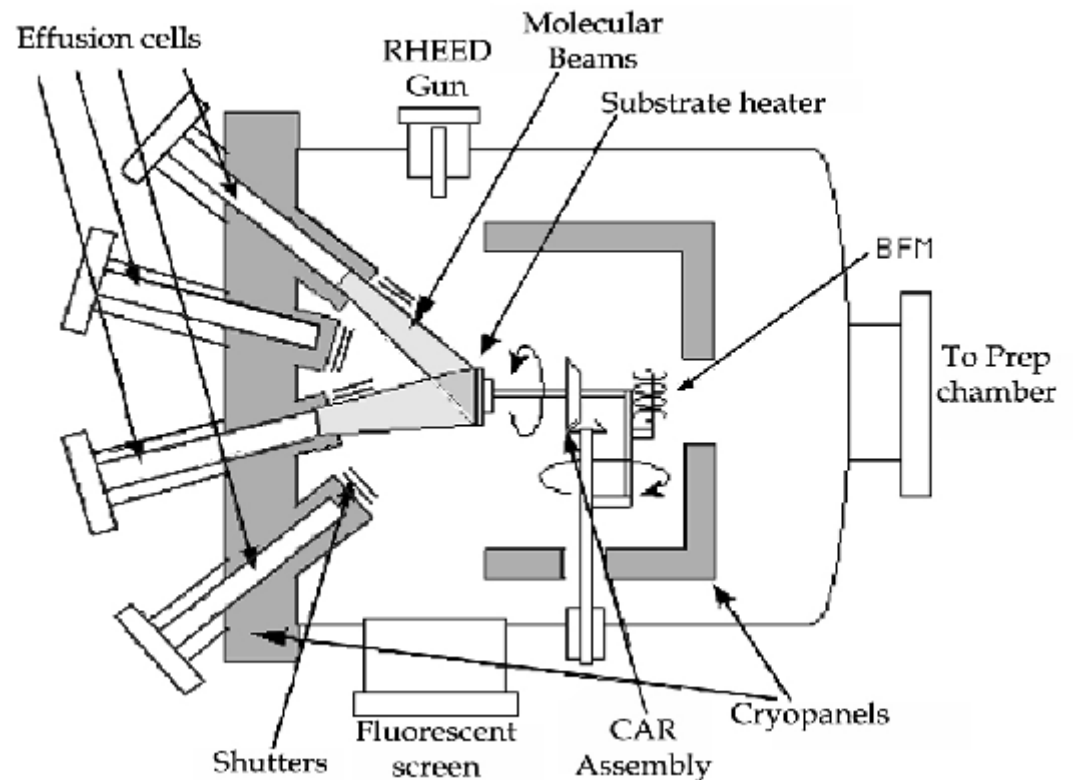


Experiments

- Molecular Beam Epitaxy
 - grow thin films of extreme precision

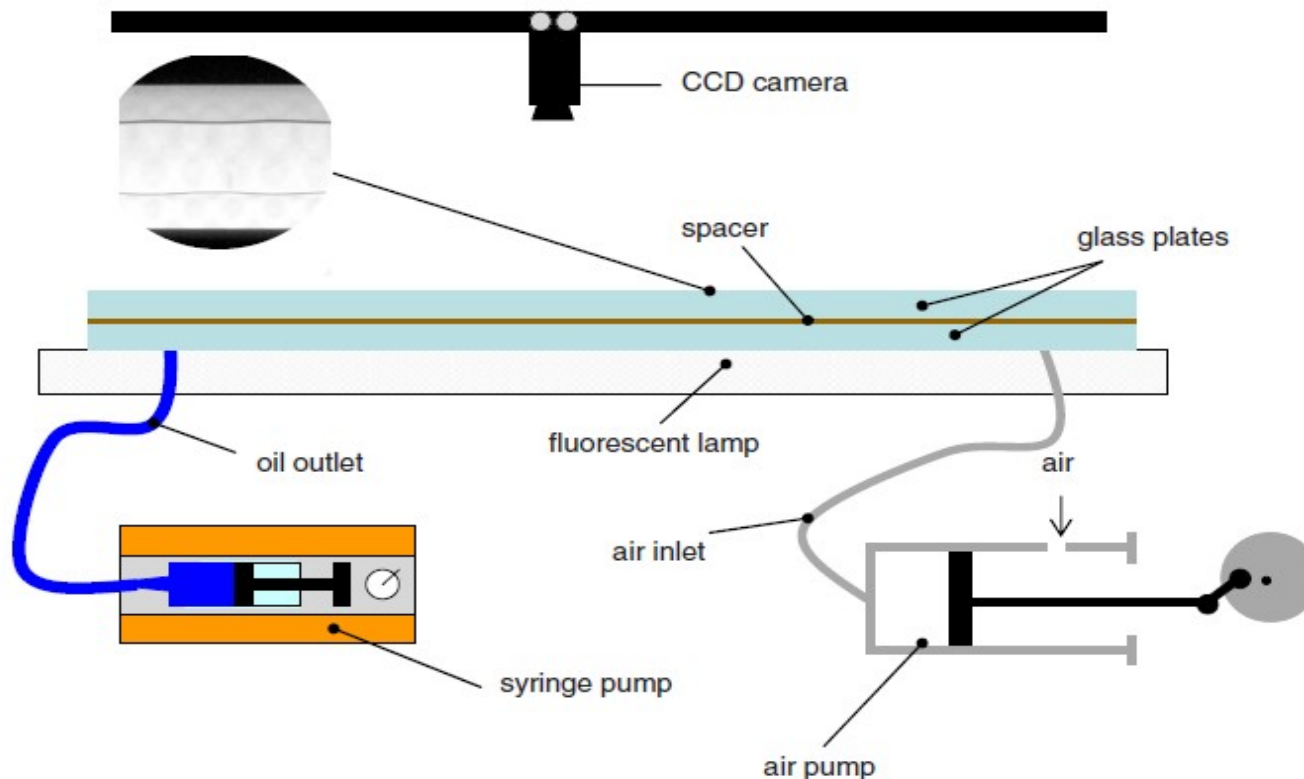


Sketch into a MBE-UHV chamber which shows the (heatable) substrate facing to the effusion cells.



Experiments

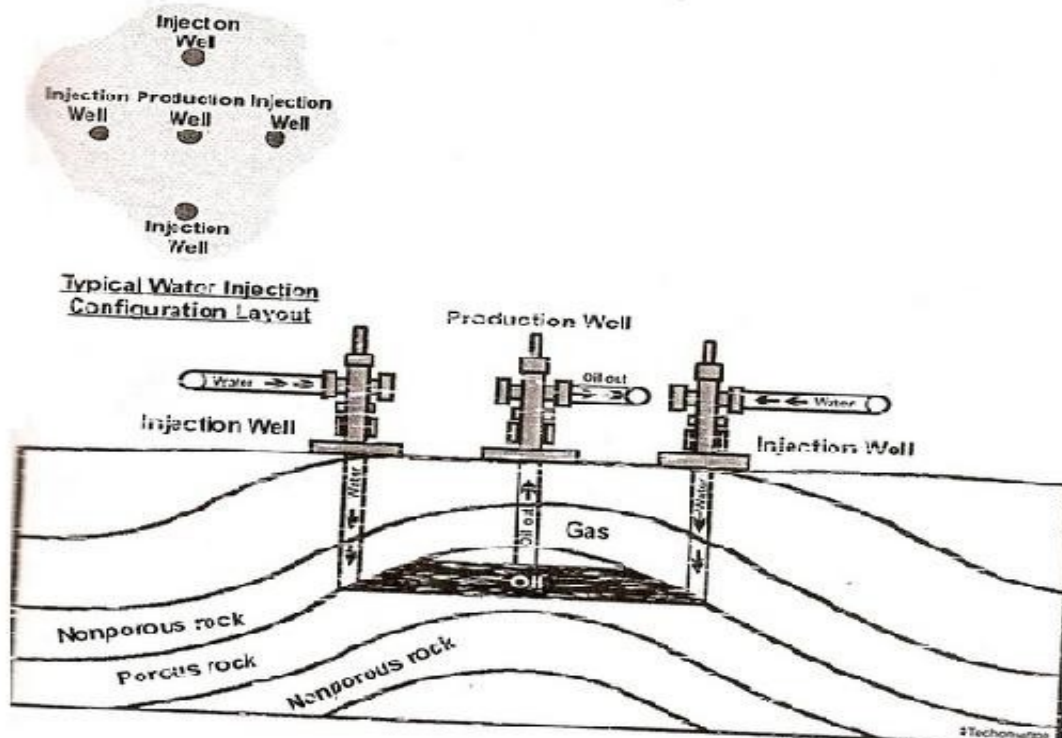
- Moving fluid/fluid interfaces (immiscible)
 - Laboratory controlled driving and disorder
 - Driven oil/air interface between rough glass plates:



Experiments

- Moving fluid/fluid interfaces (immiscible)
 - Industrial scale, rather more uncontrolled
 - Driven oil/water interface :

Water Injection



Interface Dynamics

- Approximations / Modeling

- Markovian, overdamped

$$\partial_t h(x, t) = D[h(x, t)] + \xi[h(x, t), x, t]$$

D Deterministic part (dispersion, driving)

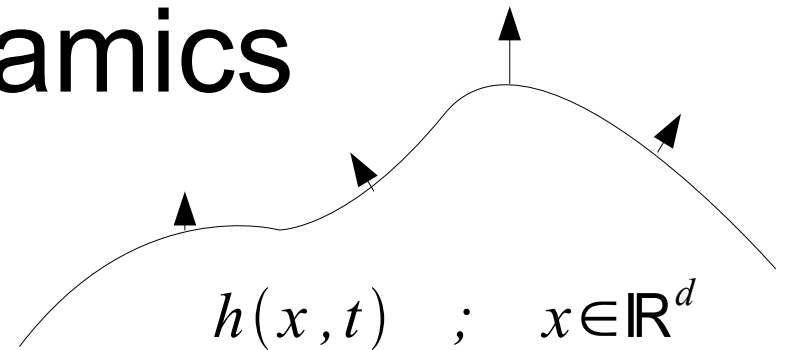
ξ Stochastic part
(disorder/noise)

- Local

$$\partial_t h(x, t) = \sum_{ij} a_{ij} \nabla^i h(x, t)^j + \xi[h(x, t), x, t]$$

- Linear

$$\partial_t h(x, t) = \sum_i a_i \nabla^i h(x, t) + \xi[h(x, t), x, t]$$



Interface Dynamics

- "Randomness" modeling

- White noise

$$\xi = \eta(x, t)$$

$$\langle \eta \rangle = 0$$

$$\langle \eta(x, t) \eta(x', t') \rangle = 2D \delta^d(x - x') \delta(t - t')$$

- Correlated noise, e.g.

$$\langle \eta(x, t) \eta(x', t') \rangle = 2D |x - x'|^{2\psi - d} |t - t'|^{2\phi - 1}$$

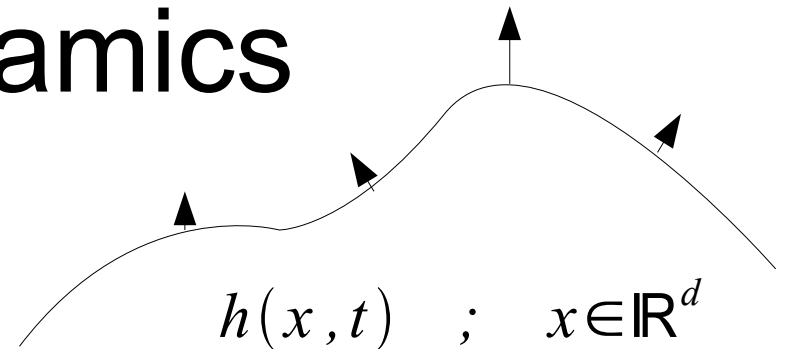
$$\langle \eta(k, \omega) \eta(k', \omega') \rangle = 2D k^{-2\psi} \omega^{-2\phi} \delta^d(k + k') \delta(\omega + \omega')$$

- Disorder field "random landscape"

$$\xi = \eta(x, h(x, t))$$

$$\langle \eta(x, y) \rangle_{x, y} = 0$$

$$\langle \eta(x, y) \eta(x', y') \rangle = 2D \delta^d(x - x') \delta(y - y')$$



Local Interface Equations

- Symmetry considerations limit terms

- Translational invariance (x, h, t) only in gradients ∇h

$$\partial_t h(x, t) = \sum_{ij} a_{ij} (\nabla^i h(x, t))^j + \xi[h(x, t), x, t]$$

- Odd gradients not rotationally symmetric in x ; **General**

$$\partial_t h = \nu \nabla^2 h + \lambda/2 (\nabla h)^2 + a_3 \nabla^4 h + a_4 (\nabla^2 h)^2 + a_5 (\nabla^2 h) (\nabla h)^2 + \dots + \xi$$

- Up/down symmetry in h , no even powers of h ; **No driving**

$$\partial_t h = \nu \nabla^2 h + a_3 \nabla^4 h + a_5 (\nabla^2 h) (\nabla h)^2 + \dots + \xi$$

Local Interface Equations

- Limit of large scales in x means only lowest derivatives that conform to symmetry
- Two most famous local interface equations
 - Edwards-Wilkinson (EW)

$$\partial_t h = \nu \nabla^2 h + \xi$$

- Kardar-Parisi-Zang (KPZ)

$$\partial_t h = \nu \nabla^2 h + \lambda/2 (\nabla h)^2 + \xi$$

Hey, what gradients?

- ξ is Wiener process (at best?), h not differentiable

Hey, what gradients?

- ξ is Wiener process (at best), h not differentiable
- Consider discrete form with finite Δx and Δt

$$\langle \eta \rangle = 0$$

$$\langle \eta(x, t) \eta(x, t') \rangle = \frac{2D}{\Delta x^d \Delta t} \delta_{xx'} \delta_{tt'}$$

$$\nabla^2 h(x, t) = \frac{1}{\Delta x^2} [h(x - \Delta x) - 2h(x, t) + h(x + \Delta x, t)]$$

- Physical matter isn't infinitely continuous
- Discrete form retains evolution processes (e.g. fluctuation/dissipation, stability/instability)
- Careful if we want to use mathematical tools - supposedly
- Δx and Δt can be relevant scales

Characterizing an interface

Time series:

- Width

$$w(L, t) = \sqrt{\left\langle (h(x, t) - \langle h(t) \rangle_L)^2 \right\rangle_L}$$

- Scaling (Family/Vicsek)

- Initially, width grows

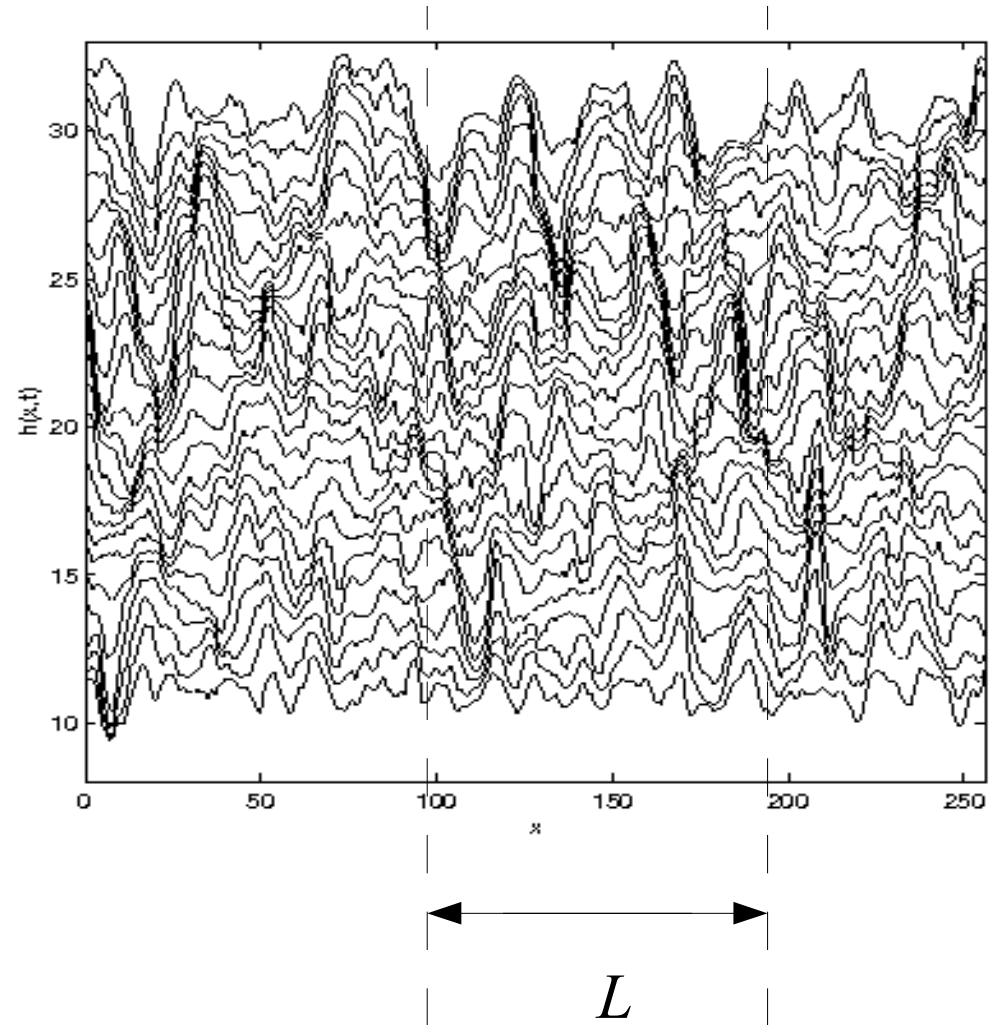
$$w(L, t) \sim t^\beta$$

- Eventually saturates

$$w_{sat}(L) \sim L^\alpha$$

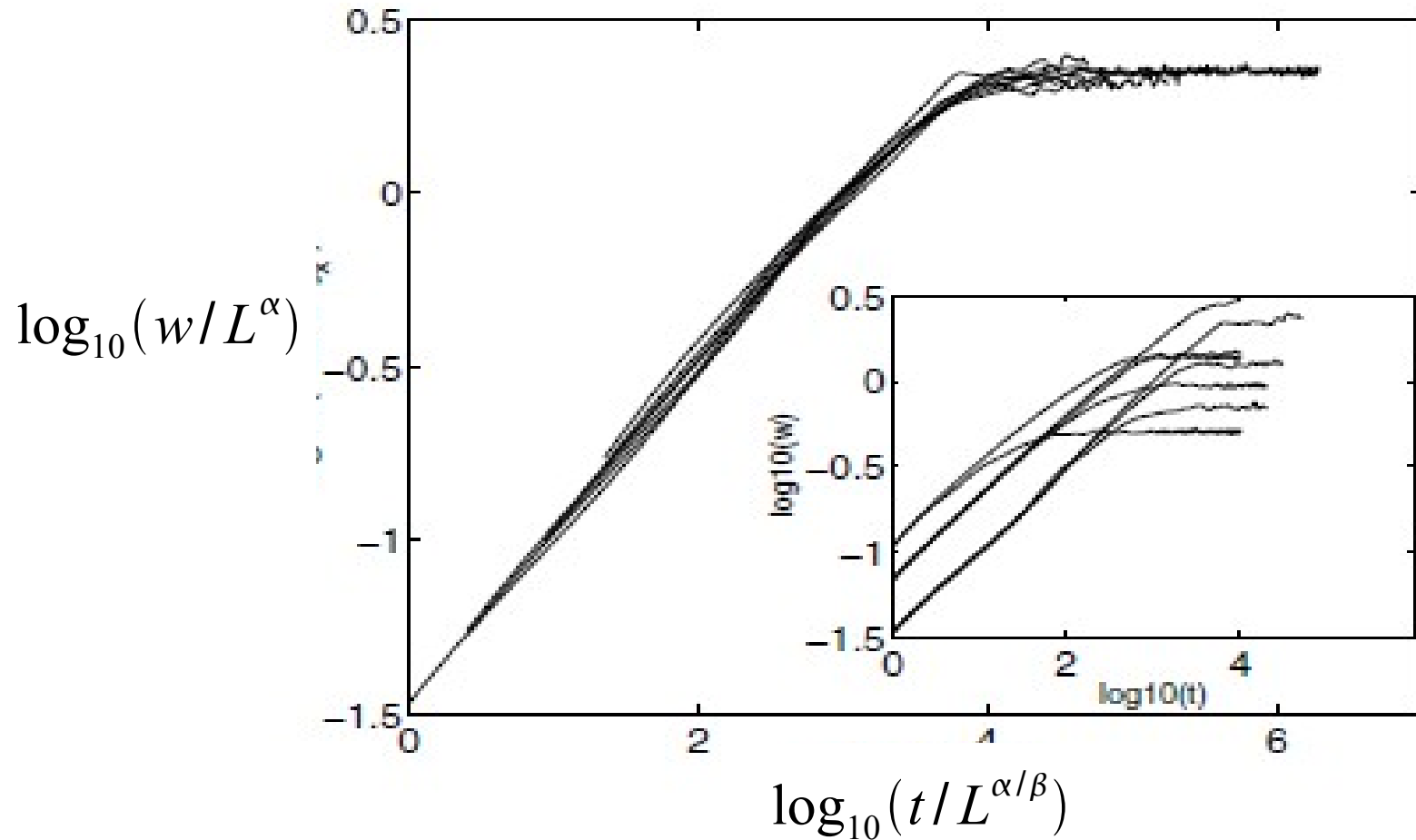
at time

$$t_X \sim L^{\alpha/\beta}$$



Scaling

- α Roughness Exponent
- β Growth Exponent



EW and KPZ

- Edwards-Wilkinson equation is linear

$$\partial_t h = \nu \nabla^2 h + \xi$$
$$\Leftrightarrow h(k, \omega) = \frac{\xi(k, \omega)}{\nu k^2 - i\omega}$$

- In case of white noise $\alpha = \frac{2-d}{2}$; $\beta = \frac{2-d}{4}$

- Kardar-Parisi-Zhang eq is non-linear

$$\partial_t h = \nu \nabla^2 h + \lambda/2 (\nabla h)^2 + \xi$$

- No exact solution, even for white noise
- Dynamic RG is exact in $d=1$ $\alpha = \frac{1}{2}$; $\beta = \frac{1}{3}$
- Numerical results for $d > 1$

Universality Classes

- Local interface equations (LIE) can be classified to universality classes
 - Assuming large scale limit (lowest gradients only)
 - Assuming white noise
 - Based on conservation of volume under interface
 - Local relaxation conserved/non-conserved
 - Noise conserved/non-conserved
 - Linear/non-linear
 - Linear, conserved $\nabla^2 h$, $\nabla^4 h$
 - Non-linear, conserved $\nabla^2 (\nabla h)^2$
 - Non-linear, non-conserved $(\nabla h)^2$

(Non-)Conserved Noise

$$\langle \eta \rangle = 0$$
$$\langle \eta(x, t) \eta(x', t') \rangle = 2D \delta^d(x - x') \delta(t - t')$$

- Non-conserved noise (random additions)

$$\partial_t h(x, t) = D[h(x, t)] + \eta(x, t)$$

- Conserved noise (random potential and flux)

$$\partial_t h = D[h(x, t)] + \nabla \cdot \vec{j} \quad ; \quad \vec{j} = \nabla \eta(x, t)$$
$$\Leftrightarrow \partial_t h = D[h(x, t)] + \nabla^2 \eta(x, t)$$

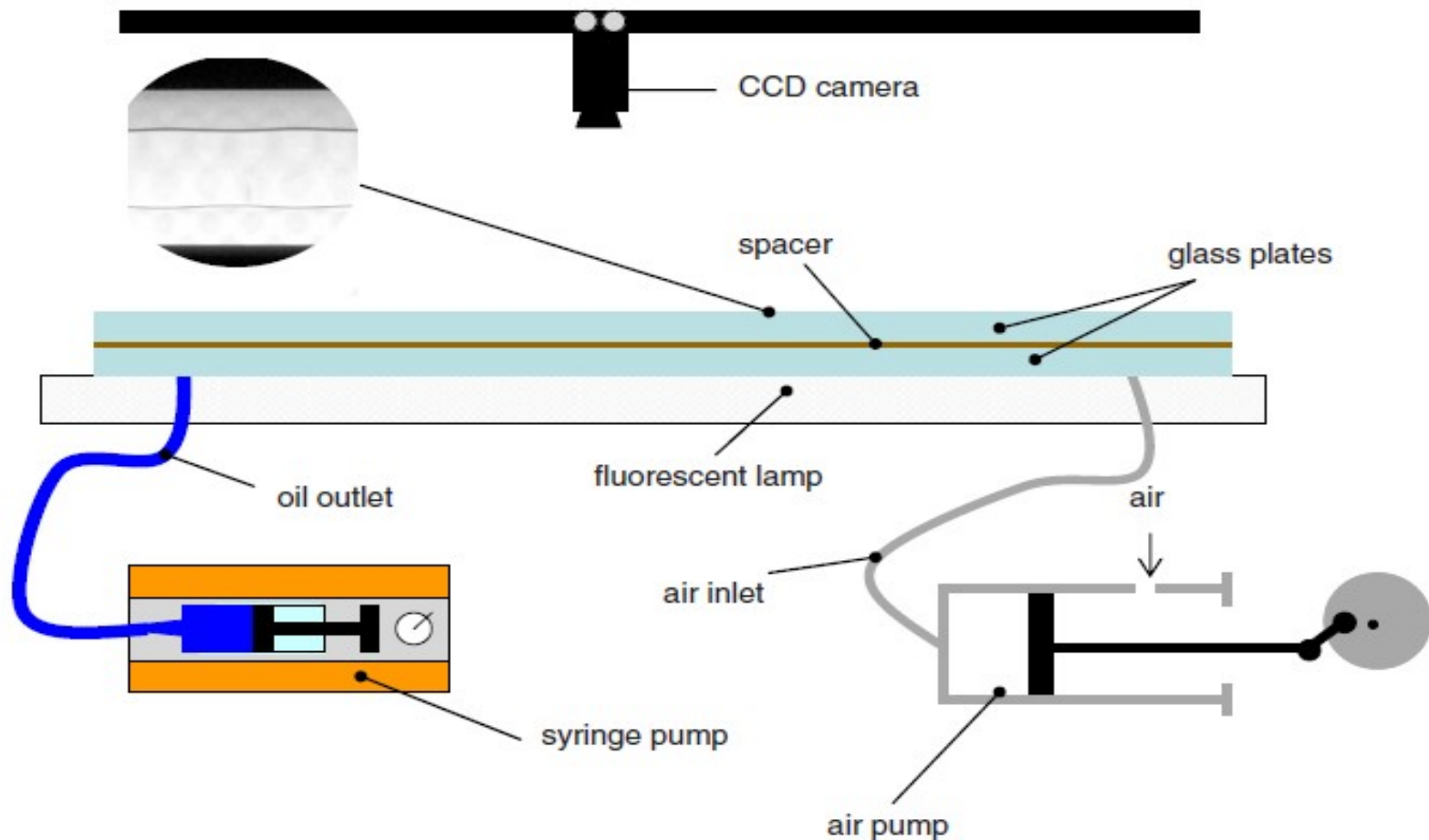


Summary of LIEs

- Assuming
 - Locality of interface relaxation processes
 - Dominance of long wavelength limit
 - Uncorrelated conserved/non-conserved noise
- Interface dynamics can be described by LIEs
- LIEs can be classified to 7 universality classes
- Universality classes describe a wide range of (simple) discrete growth models
- Observed interfaces in nature don't follow these classes "universally"

Case of the Hele-Shaw cell : Liquid/air interface in a rough channel

- Oil is driven to to a narrow, varying gap



Modeling

- Slow flow: $\mu \sim$ pressure

- Laplace's Eq. in bulk
- Darcy's law for flow

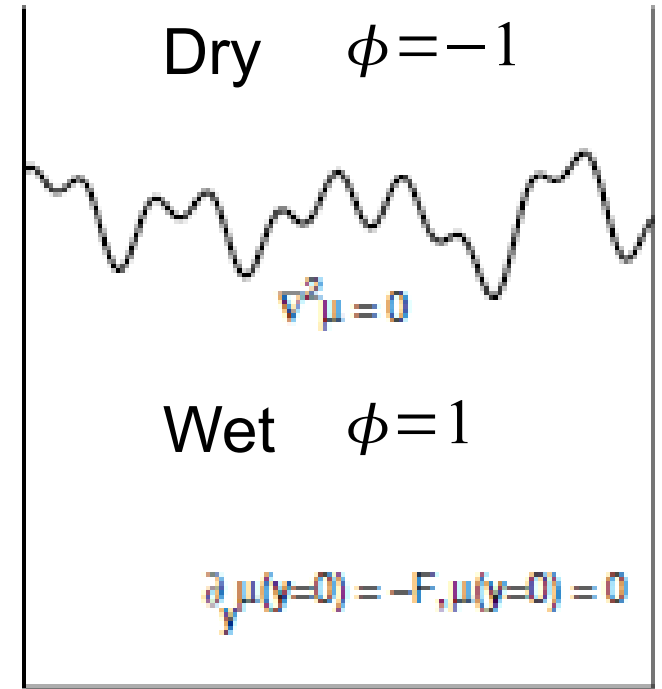
$$\vec{j} = M \nabla \mu$$

$H(x,t)$

- Driving at bottom $\nabla \mu = \text{const.}$

- **Mass conservation**

$$\partial_t \phi = \nabla \cdot \vec{j}$$



- Interface between wet/dry

$$\mu = \frac{\delta F}{\delta \phi} + \eta \quad ; \quad F[\phi] = \frac{1}{2} (\nabla \phi)^2 + V(\phi)$$

Random field

Surface tension

Bulk wet or dry

Driving

L

Modeling

- We get a model for slow propagation of oil in channel

$$\partial_t \phi(x, t) = \nabla^2 [-\nabla^2 \phi(x, t) + \phi(x, t)^3 - \phi(x, t) + \eta(x)]$$

- $\phi \sim$ oil density ; **Conservation law in 2D**
- Potential flow (=slow), and we can invert ∇^2
- $\phi(x) \sim \tanh(x)$ solves $-\nabla^2 \phi(x, t) + \phi(x, t)^3 - \phi(x, t) = 0$
- Dynamics of small perturbations of interface can be determined with projection techniques

Dynamics of interface fluctuations

- Dispersion relation for small fluctuations becomes

$$H(x, t) = H_0(t) + h(x, t)$$

$$\dot{H}_0 = \text{const.}$$

$$(1 + e^{-2|k|H_0}) \partial_t h(k, t) = -[|k|(1 - e^{-2|k|H_0}) \dot{H}_0 + \sigma |k^3|] h(k, t) + |k| \eta_k(t)$$

- Or far away from oil injection (Large H)

$$\partial_t h(k, t) = -[|k| \dot{H}_0 + \sigma |k^3|] h(k, t) + |k| \eta_k(t)$$

Conservation law Capillary waves Effective random field

- Mass conservation in 2D \neq "conserved dynamics"
- Not local in x

Dynamics of interface fluctuations

- Crossover length acts as L

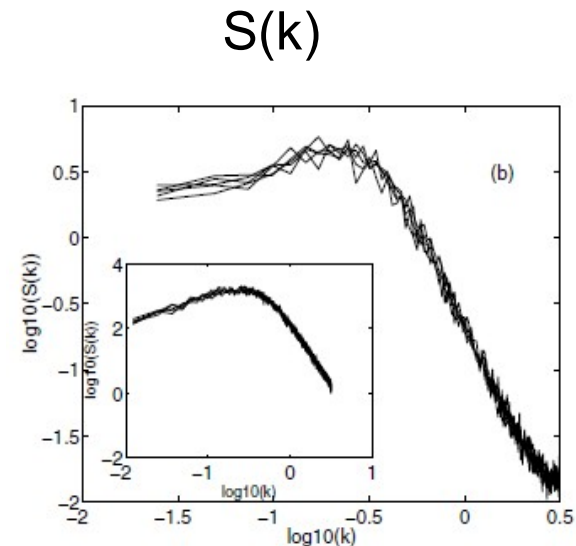
$$\xi_X = 2\pi \sqrt{\frac{\sigma}{\dot{H}_0}}$$

- Interface is super-rough at $dx < \frac{1}{k} < \xi_X$
Numerically $\alpha \simeq 1.3$

- Effective disorder not local

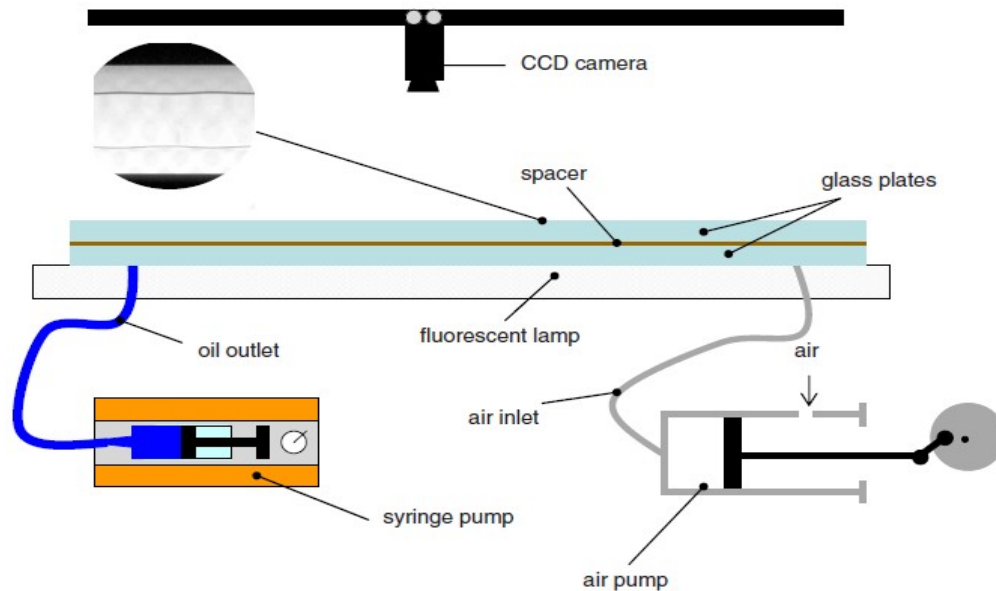
$$\tilde{\eta}(x, t) = \int dk e^{ikx} |k| \eta_k(t) = \int dk e^{ikx} |k| \int dx' e^{-ikx'} \eta(x', H(x', t))$$

- Local in time because $2D \Leftrightarrow 1D$ is bijective



More detailed modeling

- Above glass plate roughness modeled as additive stochastic term in potential μ



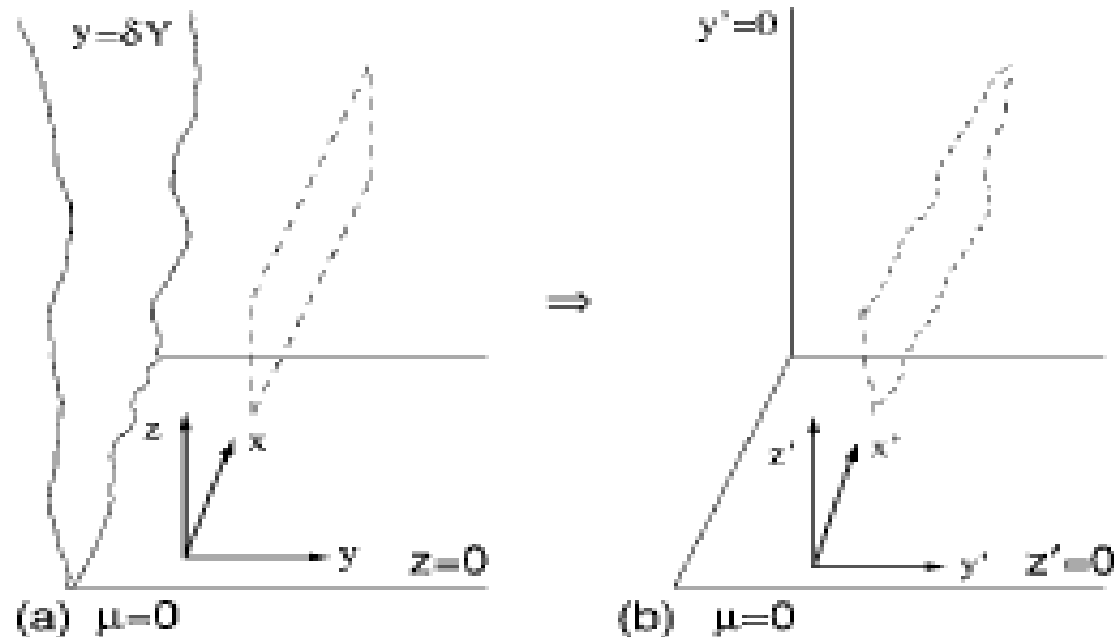
- A stochastic geometry can be modeled directly

PDE in stochastic geometry

- Our deterministic model in 3D with a rough wall

$$\partial_t \phi(x, t) = \nabla^2 [-\nabla^2 \phi(x, t) + \phi(x, t)^3 - \phi(x, t)]$$

- Perturb the Green's function of the Laplacian ∇^2
 - Turns the stochastic boundary location to an algebraic noise term



PDE in stochastic geometry

- Effective noise close to a rough wall in 3D turns out

$$\eta_k(t) = |\vec{k}| \dot{H}_0 \delta \tilde{Y}(\vec{k}, H_0)$$

- Character of modeled μ disorder persist
 - 2D model good enough

Summary of oil/air model

- Numerical solution of the two-phase model in agreement with experiments
 - J.Soriano et al. : PRE **67**, 056308 ; PRE **66**, 031603
 - T. Laurila et al. : EPJB **46**, 553 ; PRE **74**, 041601
- Detailed model exposes the difficult character of the interface equation
 - Non-local eqs; Complicated effective stochastic term (even at linear level in perturbations)
- Difficulty result from projection to 1D
 - Describing the interface only in terms of itself embeds processes in bulk to interface dynamics.

Summary

- Morphology and evolution of rough interfaces is characterized by power law scaling
 - Roughness and growth exponents
- Limited number of neatly classified LIEs characterize local interface dynamics
 - Generally real systems are (far) more complex
- Detailed study of physics of Hele-Shaw experiment reveal some insight to the complexity
 - Description of simple dynamics of a complex system turns to complicated dynamics of a simple, coarse system
 - Dynamics of a complex system cause correlated, colored noise when observed at variables of coarse-level model.

More experiments and modeling of disorder

- Recent reviews:
 - Alava, Niskanen, *Physics of Paper*, Reports of Progress in Physics **69**, 669 (2006)
 - Alava, Dube, Rost, Imbibition in Disordered Media, Advances in Physics **113**, 83 (2004).